## **Code Samples**

This chapter introduces some code samples for developers' reference and learning.

Project Name	Project Profile	Address
qisdk-tutorials	QiSDK Getting Started, contains the vast majority of robotics functionality, first time developers of robotics applications should refer to this sample code	link
qisdk-sample- return-to-map- frame	Calculates a map of the environment, uses the map to allow the robot to locate itself, and returns the robot to the original point	link
qisdk-sample- chatbot	Use both qichatbot and DialogFlow chatbot for chatbot	link
qisdk-sample- attention-state- checker	A small game where a bot makes a person look in a certain direction and checks if the direction is correct	link
qisdk-sample-what- do-you-see	How to recognise objects with Pepper camera and Tensor Flow	link